3A, 23V, 340kHz Synchronous Step-Down Converter

General Description

The RT8250 is a high-efficiency synchronous step-down DC/DC converter that can deliver up to 3A output current from 4.5V to 23V input supply. The RT8250's current mode architecture and external compensation allow the transient response to be optimized over a wide range of loads and output capacitors. Cycle-by-cycle current limit provides protection against shorted outputs and soft-start eliminates input current surge during start-up. The RT8250 also provides output under voltage protection and thermal shutdown protection. The low current (<3 μ A) shutdown mode provides output disconnection, enabling easy power management in battery-powered systems.

Ordering Information

RT8250

Package Type
 SP : SOP-8 (Exposed Pad-Option 1)

Lead Plating System
 G : Green (Halogen Free and Pb Free)

Note :

Richtek products are :

- RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- Suitable for use in SnPb or Pb-free soldering processes.

Marking Information

RT8250 GSPYMDNN RT8250GSP : Product Number YMDNN : Date Code

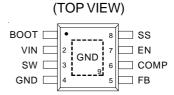
Features

- 4.5V to 23V Input Voltage Range
- 1.5% High Accuracy Feedback Voltage
- 3A Output Current
- Integrated N-MOSFET Switches
- Current Mode Control
- Fixed Frequency Operation : 340kHz
- Output Adjustable from 0.925V to 20V
- Up to 95% Efficiency
- Programmable Soft-Start
- Stable with Low-ESR Ceramic Output Capacitors
- Cycle-by-Cycle Over Current Protection
- Input Under Voltage Lockout
- Output Under Voltage Protection
- Thermal Shutdown Protection
- Thermally Enhanced SOP-8 (Exposed Pad) Package
- RoHS Compliant and Halogen Free

Applications

- Industrial and Commercial Low Power Systems
- Computer Peripherals
- LCD Monitors and TVs
- Green Electronics/Appliances
- Point of Load Regulation of High-Performance DSPs, FPGAs and ASICs.

Pin Configurations



SOP-8 (Exposed Pad)



Typical Application Circuit

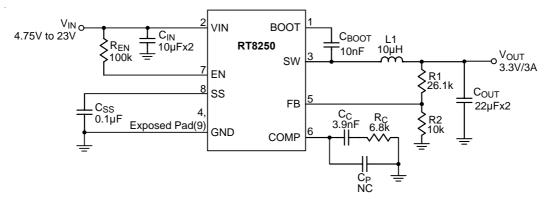


Table 1. Recommended Component Selection

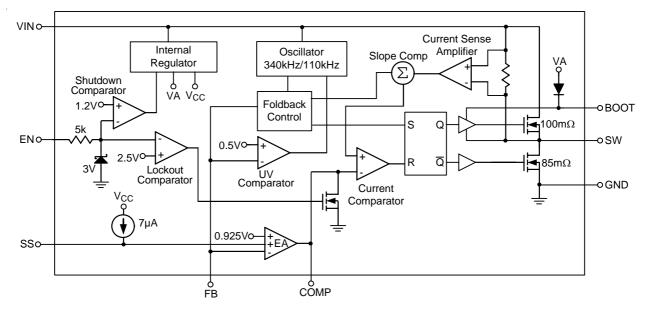
Vout (V)	R1 (kΩ)	R2 (kΩ)	Rc (kΩ)	Cc (nF)	L (µH)	Couτ (μF)
15	153	10	30	3.9	33	22 x 2
10	97.6	10	20	3.9	22	22 x 2
8	76.8	10	15	3.9	22	22 x 2
5	45.3	10	13	3.9	15	22 x 2
3.3	26.1	10	6.8	3.9	10	22 x 2
2.5	16.9	10	6.2	3.9	6.8	22 x 2
1.8	9.53	10	4.3	3.9	4.7	22 x 2
1.2	3	10	3	3.9	3.6	22 x 2

Functional Pin Description

Pin No.	Pin Name	Pin Function
1	воот	Bootstrap for High Side Gate Driver. Connect a 10nF or greater ceramic capacitor
1		from the BOOT pin to SW pin.
2	VIN	Voltage Supply Input. The input voltage range is from 4.5V to 23V. A suitable large
Z	VIIN	capacitor must be bypassed with this pin.
3	SW	Switching Node. Connect the output LC filter between the SW pin and output load.
4,		Ground. The exposed pad must be soldered to a large PCB and connected to
9 (Exposed Pad)	GND	GND for maximum power dissipation.
5	FB	Output Voltage Feedback Input. The feedback reference voltage is 0.925V
5		typically.
		Compensation Node. This pin is used for compensating the regulation control
6	COMP	loop. A series RC network is required to be connected from COMP to GND. If it is
		needed, an additional capacitor should be connected from COMP to GND.
	EN	Enable Input. A logic high enables the converter, a logic low forces the converter
7		into shutdown mode reducing the supply current to less than $3\mu A$. For automatic
		startup, connect this pin to VIN with a 100k Ω pull up resistor.
0		Soft-Start Control Input. The soft-start period can be set by connecting a capacitor
8	SS	from the SS to GND. A 0.1 μ F capacitor sets the soft-start period to 13ms typically.

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Function Block Diagram



Absolute Maximum Ratings (Note 1)

 Supply Voltage, V_{IN} 	–0.3V to 24V
Switching Voltage, SW	-0.3V to (V _{IN} + 0.3V)
<20ns	-0.3V to (V _{IN} + 3V)
BOOT Voltage	(V _{SW} – 0.3V) to (V _{SW} + 6V)
The Other Pins	–0.3V to 6V
• Power Dissipation, $P_D @ T_A = 25^{\circ}C$	
SOP-8 (Exposed Pad)	1.333W
Package Thermal Resistance (Note 2)	
SOP-8 (Exposed Pad), θ_{JA}	75°C/W
SOP-8 (Exposed Pad), θ_{JC}	15°C/W
Junction Temperature	150°C
Lead Temperature (Soldering, 10 sec.)	260°C
Storage Temperature Range	–65°C to 150°C
ESD Susceptibility (Note 3)	
HBM (Human Body Mode)	2kV
MM (Machine Mode)	200V

Recommended Operating Conditions (Note 4)

- 4.5V to 23V
- 0V to 5.5V
40°C to 125°C
- −40°C to 85°C



Electrical Characteristics

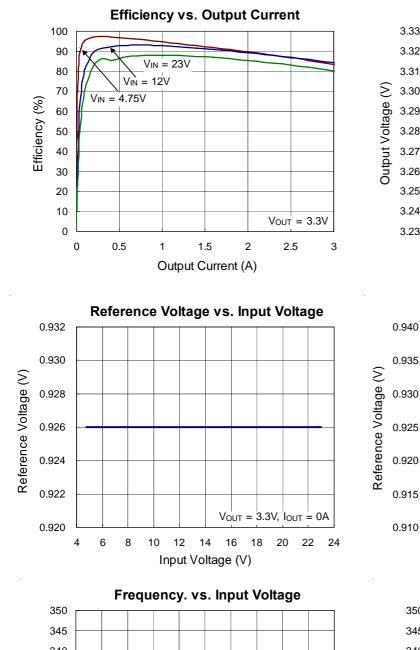
(V_{IN} = 12V, T_A = 25°C unless otherwise specified)

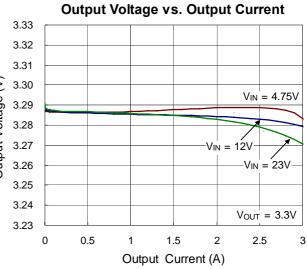
Parameter		Symbol	Test Conditions	Min	Тур	Max	Unit	
Shutdown Supply Current			V _{EN} = 0V		0.3	3	μA	
Supply Current			V _{EN} = 3 V, V _{FB} = 1V		0.7	1.2	mA	
Feedback Voltage		V _{FB}	$4.75V \le V_{IN} \le 23V$	0.911	0.925	0.939	V	
Error Amplifier Tra	nsconductance	G _{EA}	$\Delta IC = \pm 10 \mu A$		1250		μA/V	
High-Side Switch	On-Resistance	R _{DS(ON)1}			100		mΩ	
Low-Side Switch C	Dn-Resistance	R _{DS(ON)2}			85		mΩ	
High-Side Switch	Leakage Current		$V_{EN} = 0V, V_{SW} = 0V$		0	10	μA	
Upper Switch Current Limit			Min. Duty Cycle V _{BOOT} – V _{SW} = 4.8V		5.5		А	
Lower Switch Curr			From Drain to Source		1.4		А	
COMP to Current Sense Transconductance		G _{CS}			5.2		AN	
Oscillation Frequency		f _{OSC1}		300	340	380	kHz	
Short Circuit Oscillation Frequency		f _{OSC2}	$V_{FB} = 0V$		110		kHz	
Maximum Duty Cycle		D _{MAX}	$V_{FB} = 0.8V$		90		%	
Minimum On Time	•	t _{ON}			200		ns	
EN Threshold	Logic-High	V _{IH}		2.7			v	
Voltage	Logic-Low	VIL				0.4		
Input Under Voltage Lockout Threshold			V _{IN} Rising	3.8	4.2	4.4	V	
Input Under Voltage Lockout Threshold Hysterisis					200		mV	
Soft-Start Current			$V_{SS} = 0V$		7		μA	
Soft-Start Period			$C_{SS} = 0.1 \mu F$		13		ms	
Thermal Shutdown		T _{SD}			150		°C	

Note 1. Stresses listed as the above "Absolute Maximum Ratings" may cause permanent damage to the device. These are for stress ratings. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may remain possibility to affect device reliability.

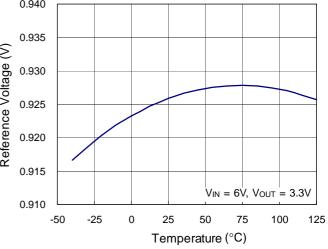
- Note 2. θ_{JA} is measured in the natural convection at $T_A = 25^{\circ}C$ on a high effective thermal conductivity four-layer test board of JEDEC 51-7 thermal measurement standard. The case position of θ_{JC} is on the exposed pad of the package.
- Note 3. Devices are ESD sensitive. Handling precaution is recommended.
- Note 4. The device is not guaranteed to function outside its operating conditions.

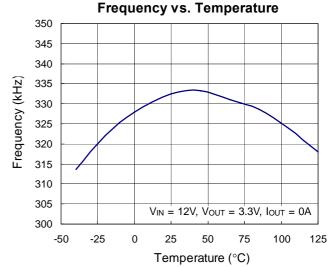
Typical Operating Characteristics

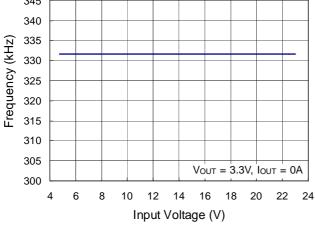




Reference Voltage vs. Temperature

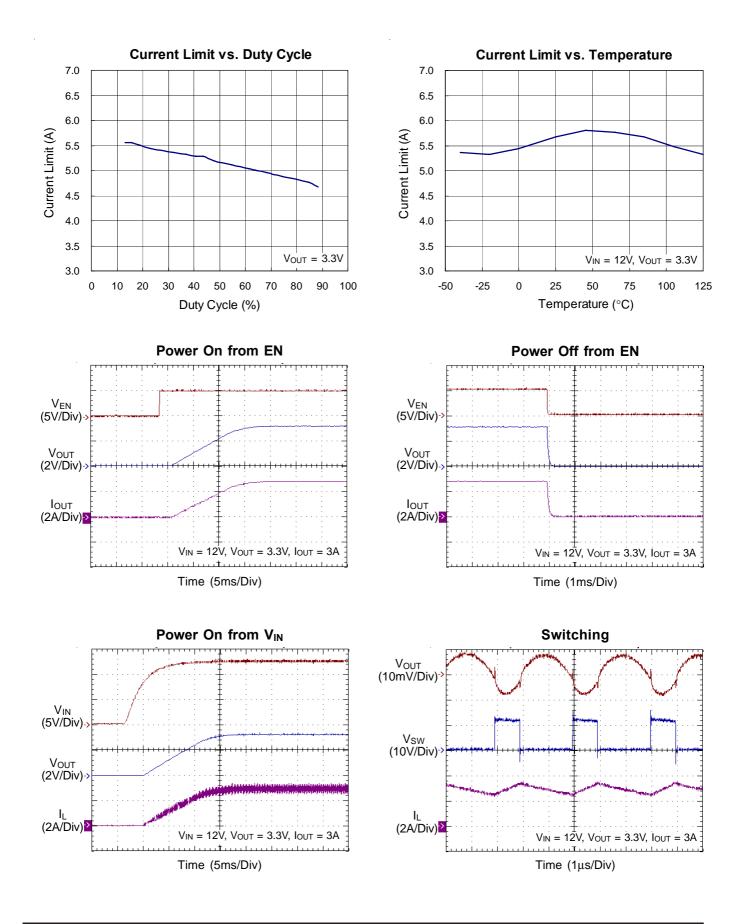




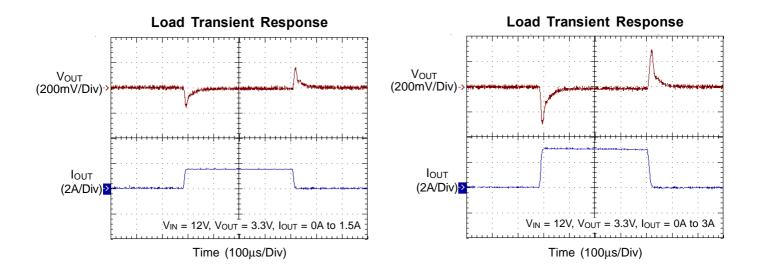


RT8250









Application Information

The RT8250 is a synchronous high voltage buck converter that can support the input voltage range from 4.5V to 23V and the output current can be up to 3A.

Output Voltage Setting

The resistive divider allows the FB pin to sense the output voltage as shown in Figure 1.

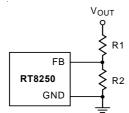


Figure 1. Output Voltage Setting

The output voltage is set by an external resistive divider according to the following equation :

 $V_{OUT} = V_{FB} \left(1 + \frac{R1}{R2} \right)$

Where V_{FB} is the feedback reference voltage (0.925V typ.).

External Bootstrap Diode

Connect a 10nF low ESR ceramic capacitor between the BOOT pin and SW pin. This capacitor provides the gate driver voltage for the high side MOSFET.

It is recommended to add an external bootstrap diode between an external 5V and the BOOT pin for efficiency improvement when input voltage is lower than 5.5V or duty ratio is higher than 65%. The bootstrap diode can be a low cost one such as 1N4148 or BAT54.

The external 5V can be a 5V fixed input from system or a 5V output of the RT8250. Note that the external boot voltage must be lower than 5.5V.

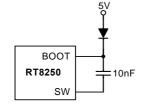


Figure 2. External Bootstrap Diode

Soft-Start

The RT8250 contains an external soft-start clamp that gradually raises the output voltage. The soft-start timming

can be programed by the external capacitor between SS pin and GND. The chip provides a 7μ A charge current for the external capacitor. If a 0.1μ F capacitor is used to set the soft-start and its period will be 13ms(typ.).

Inductor Selection

The inductor value and operating frequency determine the ripple current according to a specific input and output voltage. The ripple current ΔI_L increases with higher V_{IN} and decreases with higher inductance.

$$\Delta I_{L} = \left[\frac{V_{OUT}}{f \times L}\right] \times \left[1 - \frac{V_{OUT}}{V_{IN}}\right]$$

Having a lower ripple current reduces not only the ESR losses in the output capacitors but also the output voltage ripple. High frequency with small ripple current can achieve highest efficiency operation. However, it requires a large inductor to achieve this goal.

For the ripple current selection, the value of $\Delta I_L = 0.2375(I_{MAX})$ will be a reasonable starting point. The largest ripple current occurs at the highest V_{IN}. To guarantee that the ripple current stays below the specified maximum, the inductor value should be chosen according to the following equation :

$$L = \left[\frac{V_{OUT}}{f \times \Delta I_{L(MAX)}}\right] \times \left[1 - \frac{V_{OUT}}{V_{IN(MAX)}}\right]$$

Inductor Core Selection

The inductor type must be selected once the value for L is known. Generally speaking, high efficiency converters can not afford the core loss found in low cost powdered iron cores. So, the more expensive ferrite or mollypermalloy cores will be a better choice.

The selected inductance rather than the core size for a fixed inductor value is the key for actual core loss. As the inductance increases, core losses decrease. Unfortunately, increase of the inductance requires more turns of wire and therefore the copper losses will increase.

Ferrite designs are preferred at high switching frequency due to the characteristics of very low core losses. So, design goals can focus on the reduction of copper loss and the saturation prevention.

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Ferrite core material saturates "hard", which means that inductance collapses abruptly when the peak design current is exceeded. The previous situation results in an abrupt increase in inductor ripple current and consequent output voltage ripple.

Do not allow the core to saturate!

Different core materials and shapes will change the size/ current and price/current relationship of an inductor.

Toroid or shielded pot cores in ferrite or permalloy materials are small and do not radiate energy. However, they are usually more expensive than the similar powdered iron inductors. The rule for inductor choice mainly depends on the price vs. size requirement and any radiated field/ EMI requirements.

\textbf{C}_{IN} and \textbf{C}_{OUT} Selection

The input capacitance, C_{IN} is needed to filter the trapezoidal current at the source of the high side MOSFET. To prevent large ripple current, a low ESR input capacitor sized for the maximum RMS current should be used. The RMS current is given by :

$$I_{RMS} = I_{OUT(MAX)} \frac{V_{OUT}}{V_{IN}} \sqrt{\frac{V_{IN}}{V_{OUT}} - 1}$$

This formula has a maximum at $V_{IN} = 2V_{OUT}$, where $I_{RMS} = I_{OUT}/2$. This simple worst-case condition is commonly used for design because even significant deviations do not offer much relief.

Choose a capacitor rated at a higher temperature than required. Several capacitors may also be paralleled to meet size or height requirements in the design.

For the input capacitor, a $10\mu F \times 2$ low ESR ceramic capacitor is recommended. For the recommended capacitor, please refer to table 3 for more detail.

The selection of C_{OUT} is determined by the required ESR to minimize voltage ripple.

Moreover, the amount of bulk capacitance is also a key for C_{OUT} selection to ensure that the control loop is stable. Loop stability can be checked by viewing the load transient response as described in a later section.

The output ripple, ΔV_{OUT} , is determined by :

$$\Delta V_{OUT} \leq \Delta I_L \left[\text{ESR} + \frac{1}{8 f C_{OUT}} \right]$$

DS8250-05 March 2011

The output ripple will be highest at the maximum input voltage since ΔI_{L} increases with input voltage. Multiple capacitors placed in parallel may be needed to meet the ESR and RMS current handling requirement. Dry tantalum, special polymer, aluminum electrolytic and ceramic capacitors are all available in surface mount packages. Special polymer capacitors offer very low ESR value. However, it provides lower capacitance density than other types. Although Tantalum capacitors have the highest capacitance density, it is important to only use types that pass the surge test for use in switching power supplies. Aluminum electrolytic capacitors have significantly higher ESR. However, it can be used in cost-sensitive applications for ripple current rating and long term reliability considerations. Ceramic capacitors have excellent low ESR characteristics but can have a high voltage coefficient and audible piezoelectric effects. The high Q of ceramic capacitors with trace inductance can also lead to significant ringing.

Higher values, lower cost ceramic capacitors are now becoming available in smaller case sizes. Their high ripple current, high voltage rating and low ESR make them ideal for switching regulator applications. However, care must be taken when these capacitors are used at input and output. When a ceramic capacitor is used at the input and the power is supplied by a wall adapter through long wires, a load step at the output can induce ringing at the input, V_{IN} . At best, this ringing can couple to the output and be mistaken as loop instability. At worst, a sudden inrush of current through the long wires can potentially cause a voltage spike at V_{IN} large enough to damage the part.

Checking Transient Response

The regulator loop response can be checked by looking at the load transient response. Switching regulators take several cycles to respond to a step in load current. When a load step occurs, V_{OUT} immediately shifts by an amount equal to ΔI_{LOAD} (ESR) also begins to charge or discharge C_{OUT} generating a feedback error signal for the regulator to return V_{OUT} to its steady-state value. During this recovery time, V_{OUT} can be monitored for overshoot or ringing that would indicate a stability problem.



Thermal Considerations

For continuous operation, do not exceed the maximum operation junction temperature 125°C. The maximum power dissipation depends on the thermal resistance of IC package, PCB layout, the rate of surroundings airflow and temperature difference between junction to ambient. The maximum power dissipation can be calculated by following formula :

 $\mathsf{P}_{\mathsf{D}(\mathsf{MAX})} = \left(\mathsf{T}_{\mathsf{J}(\mathsf{MAX})} - \mathsf{T}_{\mathsf{A}} \right) / \theta_{\mathsf{JA}}$

Where $T_{J(MAX)}$ is the maximum operation junction temperature, T_A is the ambient temperature and the θ_{JA} is the junction to ambient thermal resistance.

For recommended operating conditions specification of RT8250, the maximum junction temperature is 125°C. The junction to ambient thermal resistance θ_{JA} is layout dependent. For PSOP-8 package, the thermal resistance θ_{JA} is 75°C/W on the standard JEDEC 51-7 four-layers thermal test board. The maximum power dissipation at $T_A = 25^{\circ}$ C can be calculated by following formula :

 $\mathsf{P}_{\mathsf{D}(\mathsf{MAX})}$ = (125°C - 25°C) / (75°C/W) = 1.333W for PSOP-8 package

The maximum power dissipation depends on operating ambient temperature for fixed $T_{J(MAX)}$ and thermal resistance θ_{JA} . For RT8250 package, the Figure 3 of derating curve allows the designer to see the effect of rising ambient temperature on the maximum power dissipation allowed.

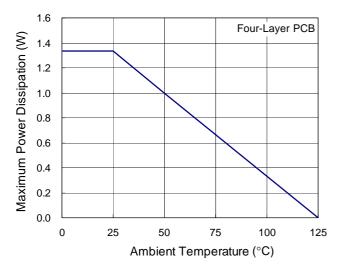


Figure 3. Derating Curve for RT8250 Package

Layout Consideration

Follow the PCB layout guidelines for optimal performance of the RT8250.

- Keep the traces of the main current paths as short and wide as possible.
- Put the input capacitor as close as possible to the device pins (VIN and GND).
- SW node is with high frequency voltage swing and should be kept at small area. Keep sensitive components away from the SW node to prevent stray capacitive noise pick-up.
- Place the feedback components to the FB pin and COMP pin as close as possible.
- The GND pin and Exposed Pad should be connected to a strong ground plane for heat sinking and noise protection.

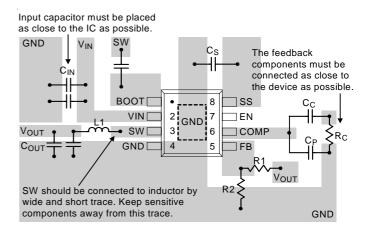


Figure 4. PCB Layout Guide

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Table 2. Suggested Inductors for Typical Application Circuit

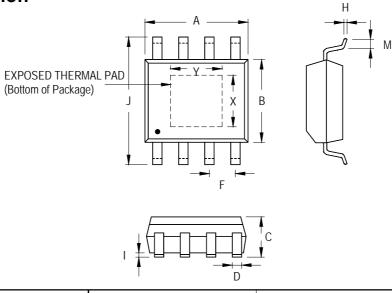
Component Supplier	Series	Dimensions (mm)	
TDK	VLF10045	10 x 9.7 x 4.5	
TAIYO YUDEN	NR8040	8x8x4	

Table 3. Suggested Capacitors for C_{IN} and C_{OUT}

Component Supplier	Part No.	Capacitance (µF)	Case Size	
MURATA	GRM31CR61E106K	10	1206	
ТDК	C3225X5R1E106K	10	1206	
TAIYO YUDEN	TMK316BJ106ML	10	1206	
MURATA	GRM31CR60J476M 47		1206	
ТDК	C3225X5R0J476M	47	1210	
TAIYO YUDEN	EMK325BJ476MM	47	1210	
MURATA	GRM32ER71C226M	22	1210	
ТDК	C3225X5R1C226M	22	1210	



Outline Dimension



Symbol		Dimensions I	n Millimeters	Dimensions In Inches		
		Min	Мах	Min	Max	
A		4.801	5.004	0.189	0.197	
В		3.810	4.000	0.150	0.157	
С		1.346	1.753	0.053	0.069	
D		0.330	0.510	0.013	0.020	
F		1.194	1.346	0.047	0.053	
Н		0.170	0.254	0.007	0.010	
I		0.000	0.152	0.000	0.006	
J		5.791	6.200	0.228	0.244	
М		0.406	1.270	0.016	0.050	
Option 1	Х	2.000	2.300	0.079	0.091	
	Y	2.000	2.300	0.079	0.091	
Option 2	Х	2.100	2.500	0.083	0.098	
	Y	3.000	3.500	0.118	0.138	

8-Lead SOP (Exposed Pad) Plastic Package

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